

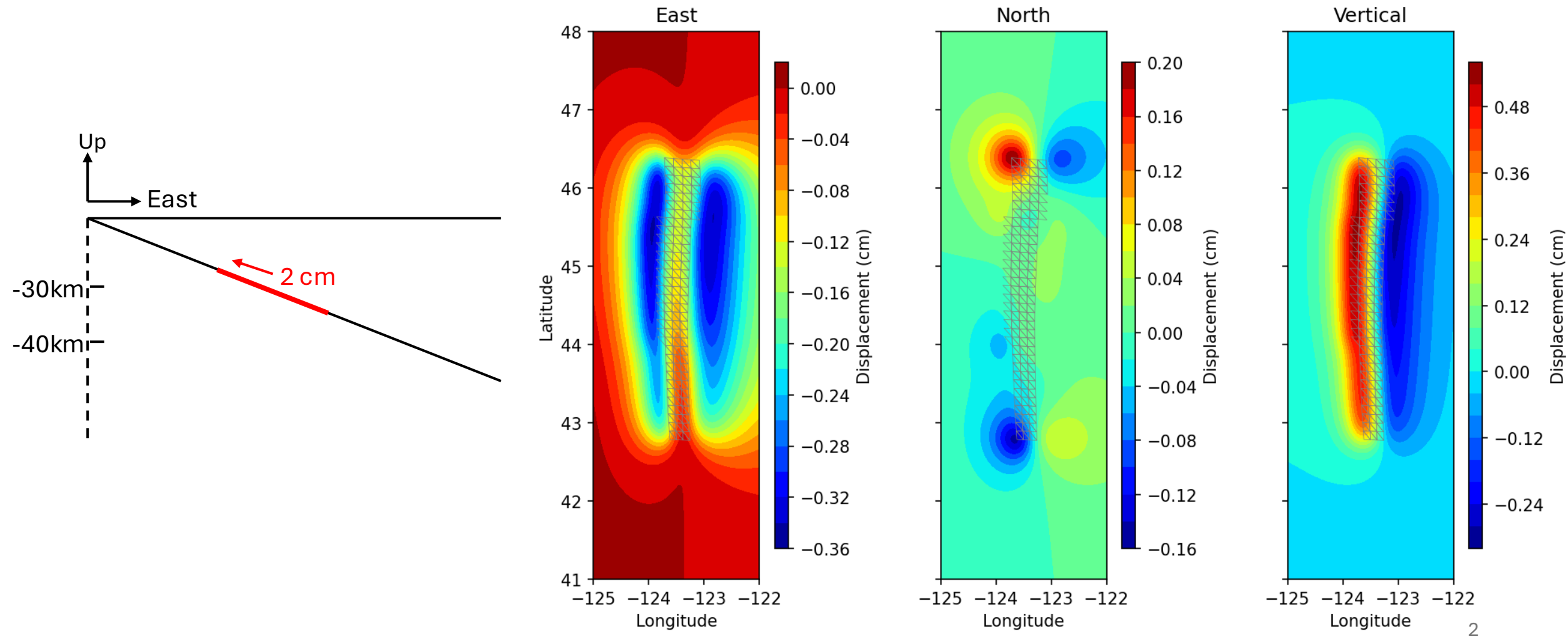
# Precise Localization and Measurement of **Slow Slip Events** in Central Cascadia with InSAR – Seed Grant Update for CRESCENT

Yujie Zheng and Eshanta Mishra  
University of Texas at Dallas  
April 21, 2026

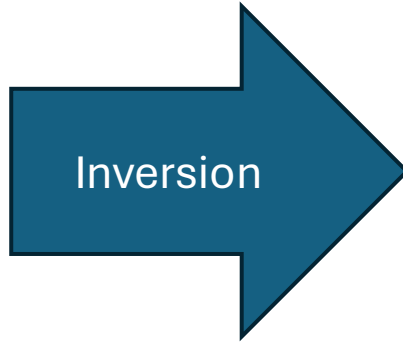
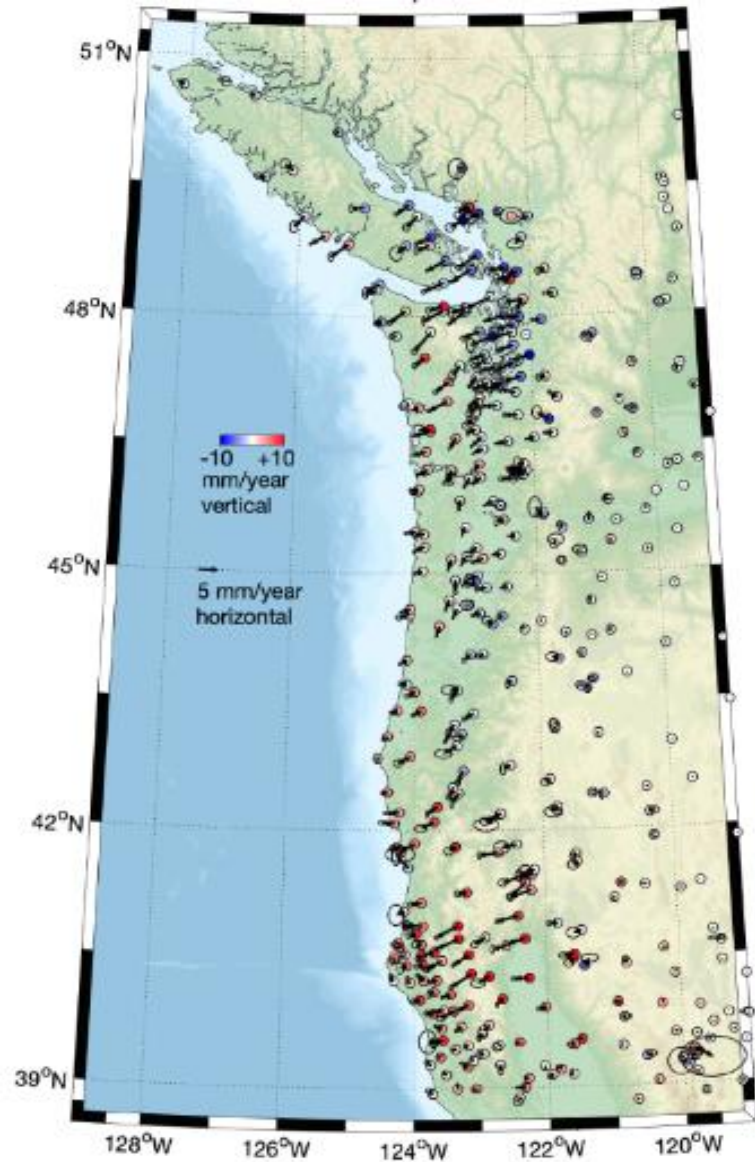


# Slow slip generates measurable deformation on the Earth's surface

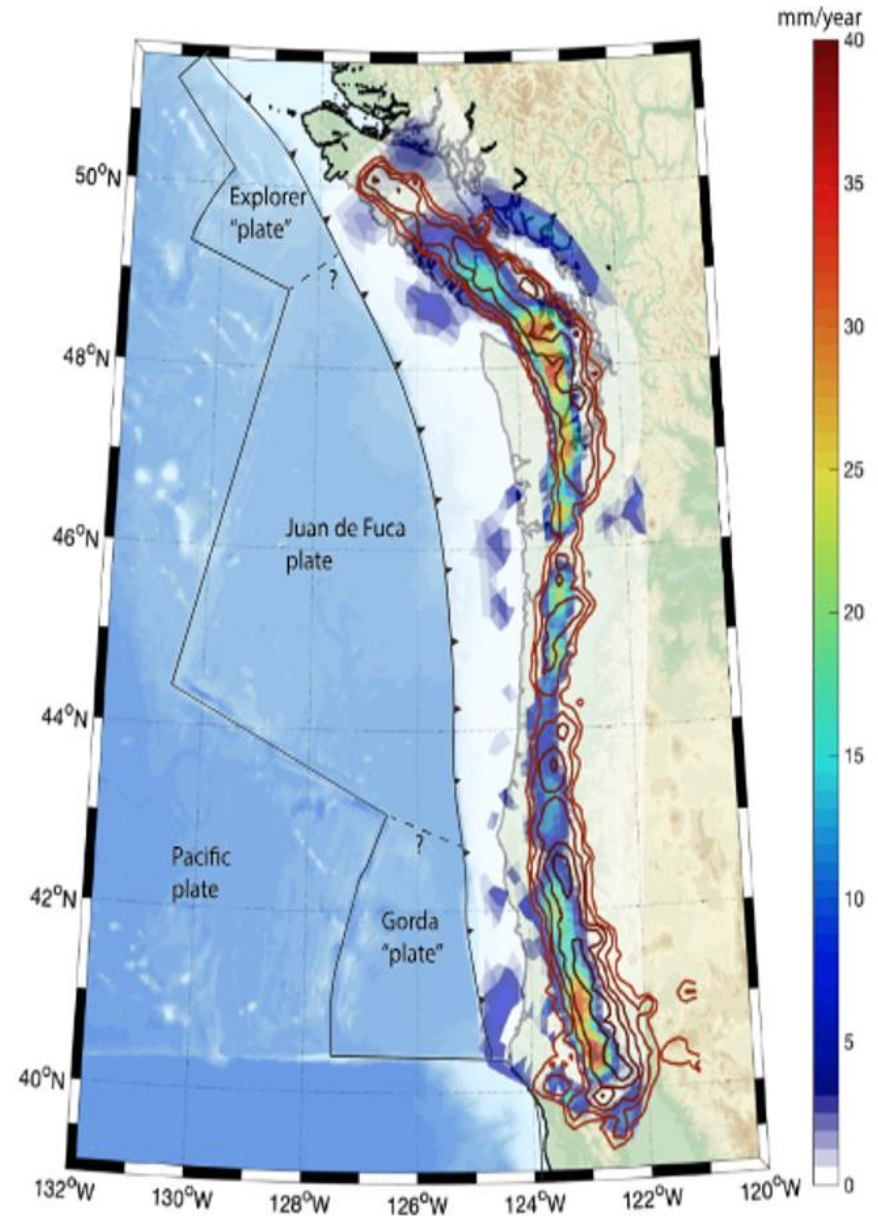
Predicted surface deformation due to 2 cm uniform updip slip between 30km to 40 km depth



# Cascadia SSEs from GNSS

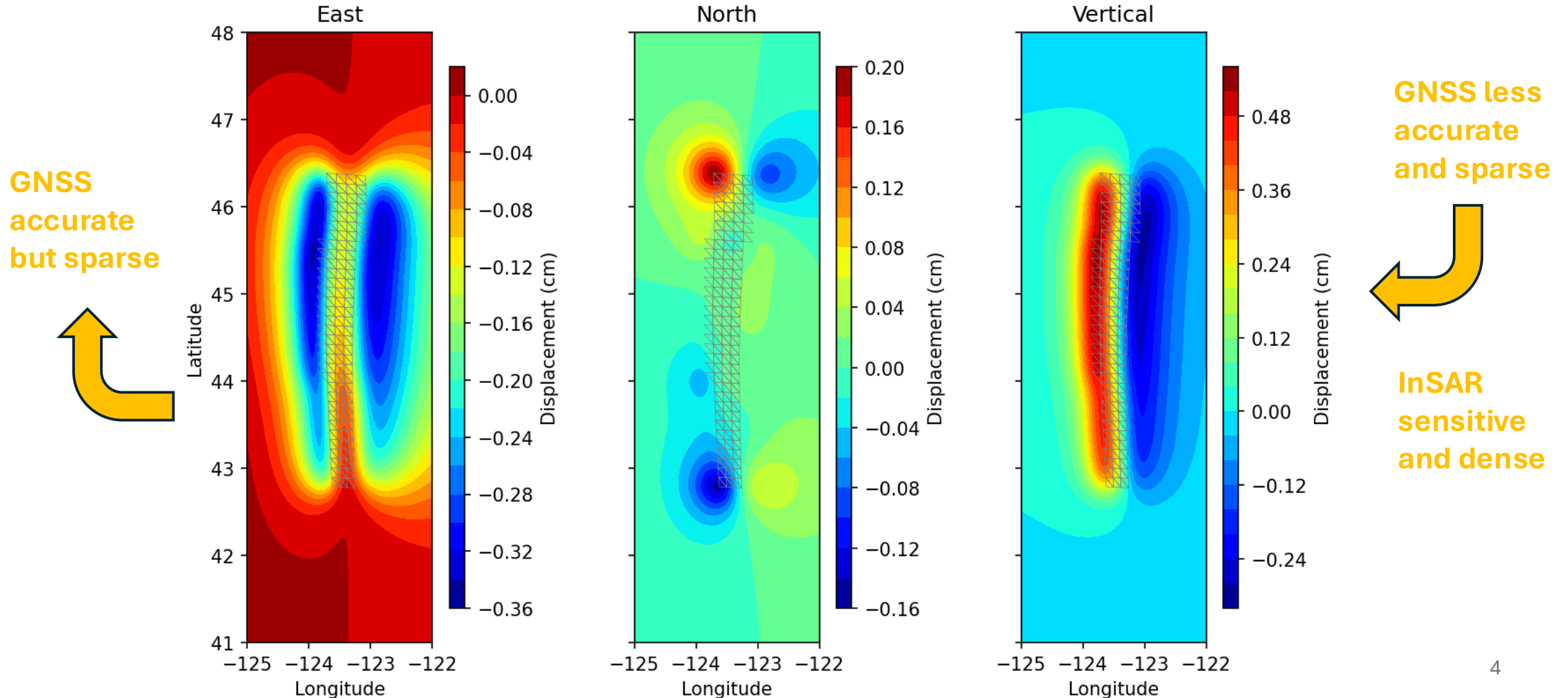


(Bartlow, 2020)

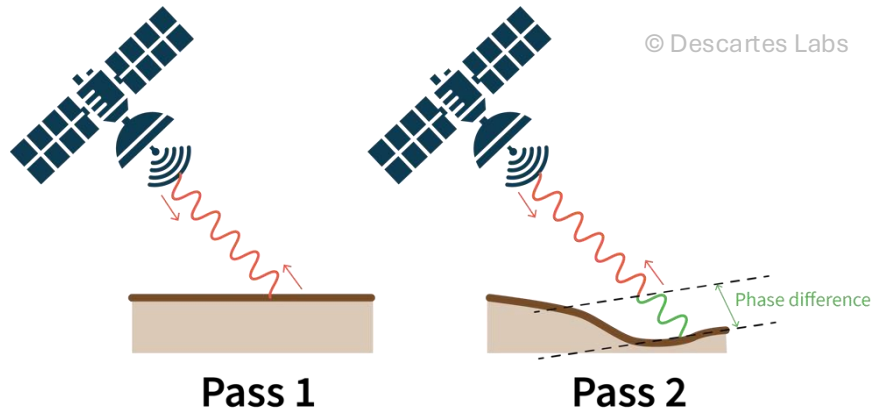


# InSAR as a Complement to GNSS for Slow Slip Inversion

Predicted surface deformation due to 2 cm uniform updip slip between 30km to 40 km depth



# InSAR measures high-resolution deformation, but noise limits accuracy



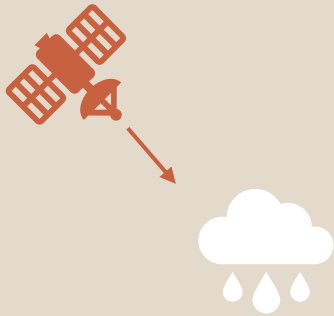
For two images acquired at times  $i$  and  $j$ ,

$$\text{Phase Change } (\Delta\phi_{ij}) = d + \epsilon_{\text{atmospheric}} + \epsilon_{\text{decorrelation}} + \epsilon_{\text{other}}$$

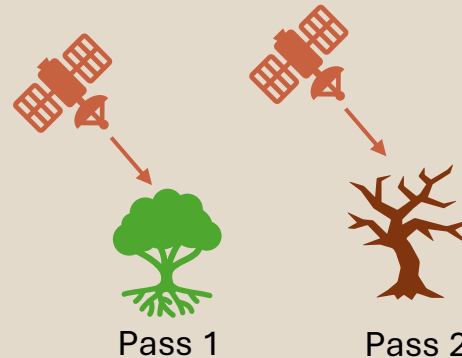
displacement

Noise

## Atmospheric Noise



## Decorrelation Noise

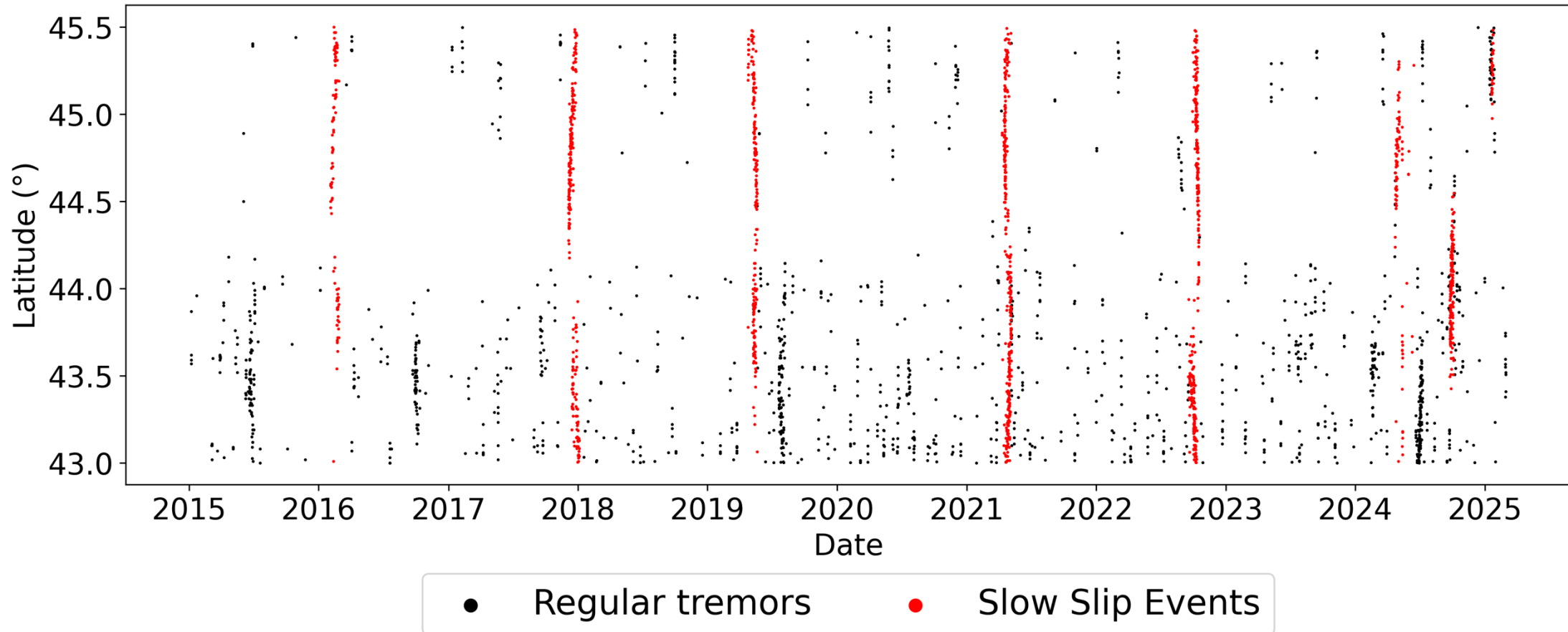


## Other Noises

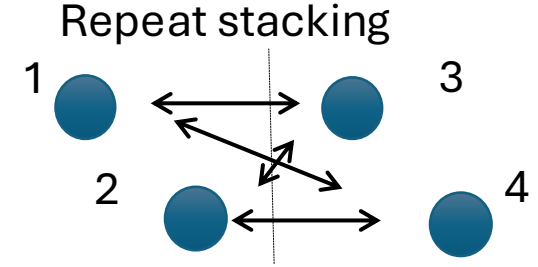
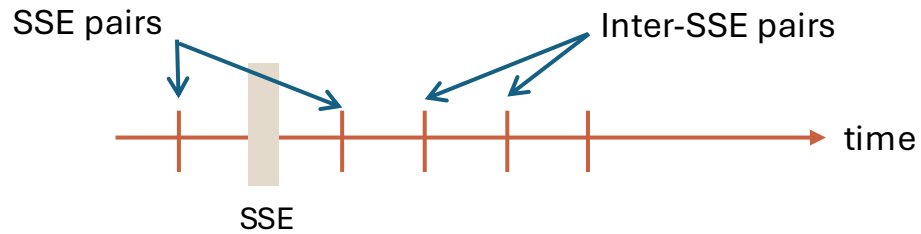
- Phase Unwrapping Errors
- Thermal Noise
- Topographic Noise

# A large but noisy InSAR dataset spanning 6 SSEs

During this time, there are 640 SAR acquisitions (Sentinel-1) at an average interval of 6 to 12 days, which correspond to more than 200k interferograms!



# Repeat-Stacking Interferograms to improve SNR



For SSE pairs,  $\Delta\phi_{SSE} = d_{SSE} + vT_{ij} + \epsilon_{\text{atmospheric}} + \epsilon_{\text{decorrelation}} + \epsilon_{\text{other}}$

Reduced by stacking
Easily estimated or negligible for modern SAR sensors

Averaging,  $\frac{\sum \Delta\phi_{SSE}}{N_{SSE}} = d_{SSE} + v \frac{\sum T_{ij_{SSE}}}{N_{SSE}} \dots\dots [1]$

For Inter-SSE pairs,  $\Delta\phi_{\text{Inter-SSE}} = vT_{ij} + \epsilon_{\text{atmospheric}} + \epsilon_{\text{decorrelation}} + \epsilon_{\text{other}}$

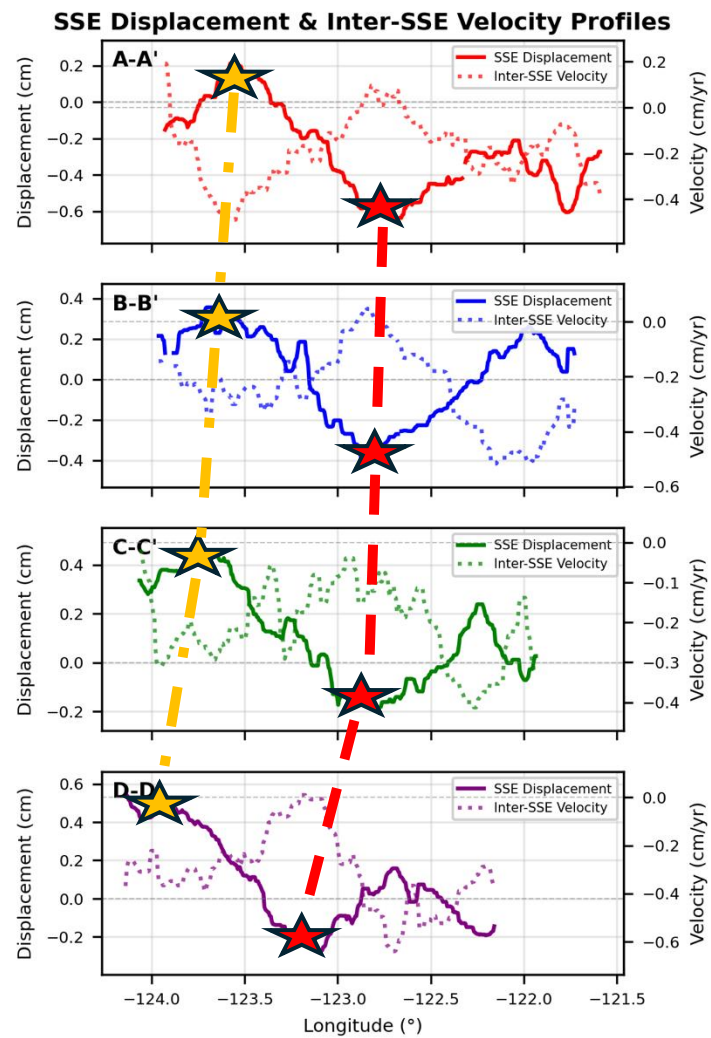
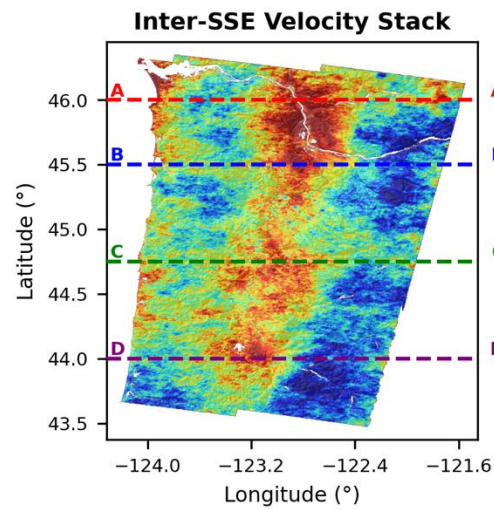
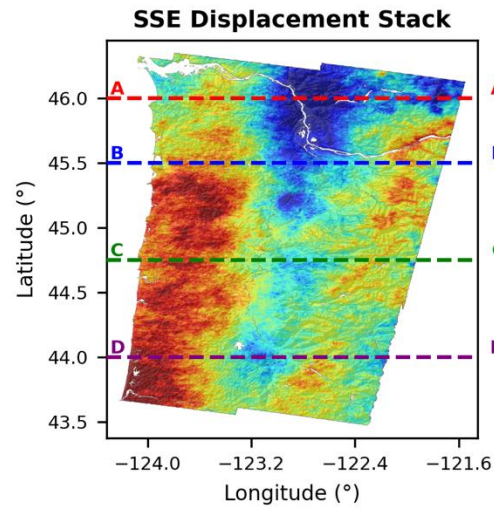
Temporally averaging,  $\frac{\sum \Delta\phi_{\text{Inter-SSE}}}{\sum T_{ij_{\text{Inter-SSE}}}} = v \dots\dots [2]$

where,

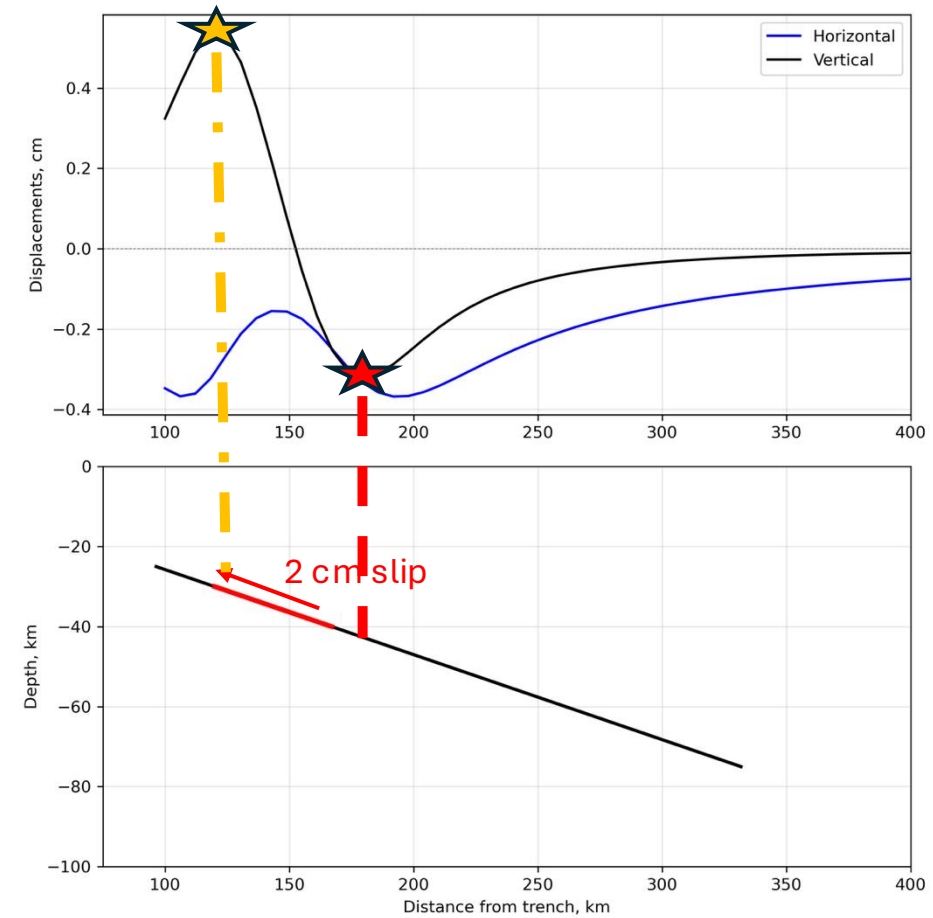
$\Delta\phi$	Phase difference in interferogram formed by $i$ & $j$ and converted to distance
$d_{SSE}$	Displacement due to the SSE (SSE signal)
$v$	Inter-SSE velocity (plate velocity)
$T_{ij}$	Temporal baseline of interferogram formed by $i$ & $j$
$\epsilon$	Noises in the interferogram
$N_{SSE}$	No. of SSE pairs

**$d_{SSE}$  can be calculated by substituting the value of  $v$  calculated from equation 2 into 1.**

# Results

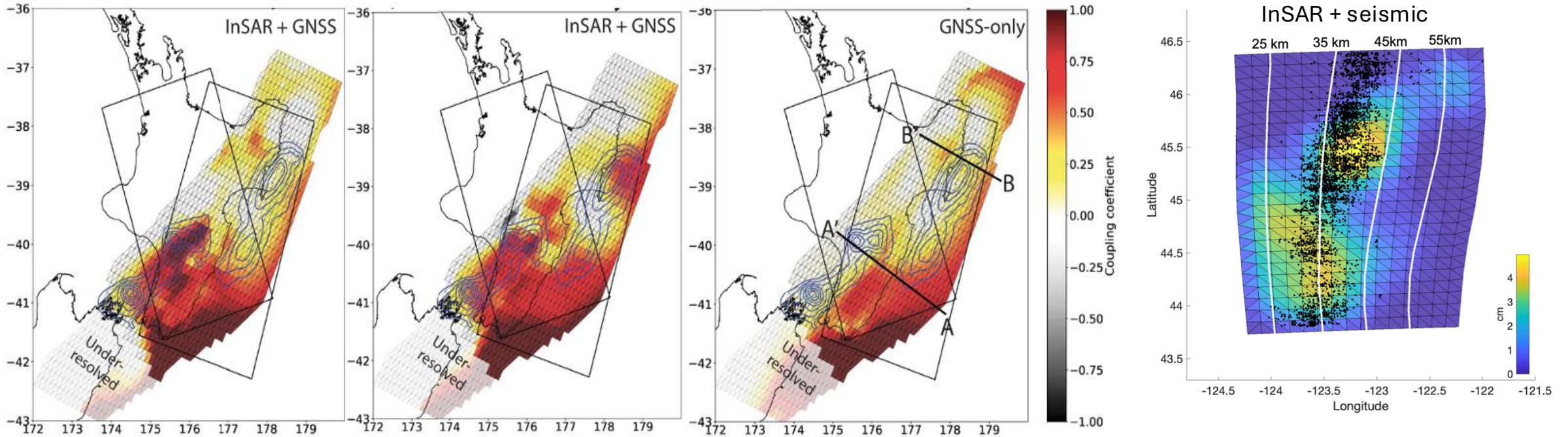


## Forward Model



# Take-aways

1. InSAR can add spatial detail and vertical sensitivity to slow slip observations in central Cascadia
2. This seed grant explores that potential and builds toward broader integration



(Maubant et. al., 2023)

Zheng, 2019

## What's Next?

1. Produce validated InSAR-derived SSE and inter-SSE deformation datasets with uncertainty estimates
2. Joint analysis of InSAR+GNSS+SEISMIC datasets
3. Assess whether InSAR can resolve temporally varying slip