

# PTHA AND COASTAL PROCESSES: Non-stationary statistics and compounding hazards

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#### PTHA AND NON-STATIONARY COASTAL PROPERTIES



A new era in coastal hazards assessments should incorporate daily-varying and non-stationary processes in time scales comparable to coastal project lifetimes.

For example, tides and the climate-change-driven sea level rise.





#### PTHA AND NON-STATIONARY COASTAL PROPERTIES

#### Even, vulnerabilities are non-stationary...









## PROBABILISTIC TSUNAMI HAZARD ASSESSMENTS AND COASTAL PROCESSES

**TSUNAMI HAZARDS AFFECTED BY COASTAL TIDES, SLR AND BATHYMETRY** 

Maximum Considered Tsunami (MCT) in ASCE 7-16: Those exceeded with probability of 2% in 50 yrs.





Should the "ASCE 7-16 Tsunami Loads and Effects" incorporate coastal influences when developing MCT maps?

## PROBABILISTIC TSUNAMI HAZARD ASSESSMENTS WITH SEA LEVEL RISE



But my future



I.e.  $p_i(H > h_c | E_i)$  and  $\lambda_i$  varying in time



m

$$P[N_{H>hc} > 0, T] = 1 - e^{-\sum_{i=1}^{n} \lambda_i p_i (H > h_c | E_i) T}$$

Let's revisit the fundamentals of the Poisson process...

Consider an infinitesimal partition of T into a sub-intervals dt, such that the probability of having 0 or 1 events is nearly 1, and a sea state s(t) varying in time. The probability of having  $P[N_{H>hc} > 0, T] = 1 - e^{-\sum_{i=1}^{n} \int_{0}^{T} \lambda_{i} p_{i}(H>h_{c}|E_{i},s(t))dt}$  $1 - p_{i}(H > h_{c}|E_{i},s(t))\lambda_{i}dt \approx e^{-\lambda_{i} p_{i}(H > h_{c}|E_{i},s(t))dt}$ 

**Non Stationary Poisson Process** 

The overall probability in T can be viewed as a sequence of independent Bernoulli trials (i.e. a product of probabilities). This is also known as the non-homogeneous Poisson process:

$$\int e^{-\lambda_i p_i} (H > h_c | E_i, s(t)) dt = e^{-\int_0^T \lambda_i p_i} (H > h_c | E_i, s(t)) dt$$

## **PROBABILISTIC TSUNAMI HAZARD ASSESSMENTS WITH SEA LEVEL RISE**

We introduce a non-stationary probabilistic tsunami hazard assessment (nPTHA)

$$P[N_{H>hc} > 0, T] = 1 - e^{-\sum_{i=1}^{n} \int_{0}^{T} \lambda_{i} p_{i}(H>h_{c}|E_{i},s(t)) dt}$$

 $p_i$  is now a function of time ( $\lambda_i$  as well if you would like). One example is the effect of sea level rise.

Great, but how do we get  $\int_0^T p_i(H > h_c | E_i, s(t)) dt ?...$ 

We apply a surrogate model





Time [yr]

**Non Stationary PTHA** 



## **PROBABILISTIC TSUNAMI HAZARD ASSESSMENTS WITH TIDES**



Incorporation of tides in nPTHA





Tidal ranges are comparable to SLR for the next few decades. It is necessary to incorporate them in the nPTHA.

$$P\left(N_{h_c}(T)=0\right) = e^{-\sum_i \lambda_{E_i} \int_0^T \int_{\eta_{min}}^{\eta_{max}} f_{\eta}(\eta) p_i(H > h_c | E_i, s(t), \eta) d\eta dt}$$
  
nPTHA with tides

The classic PTHA in Southern California



Sepulveda & Mosqueda (under review)

2

2

2.5

2.5







Let's apply the nPTHA!! We obtain the sea level rise projections and tides

#### Exceedance probabilities in 50 years can be obtained.





#### nPTHA in San Pedro Bay and San Diego (effects of tides and SLR)



242.9

242.95

2.5



## **TSUNAMI-TIDE INTERACTION**

#### **TSUNAMI-TIDE INTERACTION: THE DETERMINISTIC FULLY-COUPLED MODEL**



A fully-coupled tsunami-tide models can be built to evaluate the interaction of these processes.

dt

The computational demand for a deterministic scenario, though, is high. Demand will be much higher for nPTHA

$$\frac{\partial h}{\partial t} + \frac{\partial h\bar{u}}{\partial x} + \frac{\partial h\bar{v}}{\partial y} = 0, \qquad (1)$$

$$\frac{\partial}{\partial t}(h\bar{u}) + \frac{\partial}{\partial x}(h\bar{u}^2) + \frac{\partial}{\partial y}(h\bar{v}\bar{u}) = fh\bar{v} - gh\frac{\partial\eta}{\partial x} - \frac{n^2g\bar{u}\sqrt{\bar{u}^2 + \bar{v}^2}}{h^{\frac{1}{3}}} + \frac{\partial}{\partial x}(hT_{xx}) + \frac{\partial}{\partial y}(hT_{xy}) - h\frac{\partial\Omega}{\partial x},$$
(2)

$$\frac{\partial}{\partial t}(h\bar{v}) + \frac{\partial}{\partial x}(h\bar{u}\bar{v}) + \frac{\partial}{\partial y}(h\bar{v}^{2}) = -fh\bar{u} - gh\frac{\partial\eta}{\partial y} - \frac{n^{2}g\bar{v}\sqrt{\bar{u}^{2} + \bar{v}^{2}}}{h^{\frac{1}{3}}} + \frac{\partial}{\partial x}(hT_{yx}) + \frac{\partial}{\partial y}(hT_{yy}) - h\frac{\partial\Omega}{\partial y}, \quad (3)$$



#### **TSUNAMI-TIDE INTERACTION: THE DETERMINISTIC FULLY-COUPLED MODEL**













dt





#### **TSUNAMI-TIDE INTERACTION: THE DETERMINISTIC ONE-WAY-COUPLED MODEL**

We may simplify the problem depending on the case of study.

For example, in San Diego tide temporal variation are relevant but tidal currents are not high.

We set a one-way coupling tsunami-tide model. Tides are specified from input files...

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* COMCOT TIM	*
*	*
* Cornell Multi-grid Coupled Tsunami Tide model	*
*	*
* Version Sepu 1.8xx *	¢
* updated on 2024-10-25	G
*	*
* TIM developed by	*
*	*
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Sepulveda et al (In prep)

dt



## **TSUNAMI MODELING WITH UNCERTAIN BATHYMETRY**

f) Variance-normalized PSD v/s I



#### **SHOULD BE WORRIED?**

## Satellite bathymetry from a spectral perspective

The bathymetry exhibits a fractal behavior. It follows a power law.

This band is solved using low density ship measurements.

~15 km

Gravity anomalies, g, is linearly related with bathymetry, h.

> High wavenumber content not recovered. The errors are related with this content.



DEM partially satellite uses bathymetry or sparse ship-board soundings.

### What is the effect of errors?

Sepulveda et al (2020)

160 km

 ${}_{10}^{}(P/\sigma_{e}^{2}\,m^{2})$ 

<sup>6</sup>

H = 0.95

= 3 km error = 0.353

-4.5

-4.0

-3.5 Log<sub>10</sub>(k m<sup>-1</sup>)

Wavelengths

Power

spectral

density of

estimated

bathymetry



-19.4

-19.5

-19.6

-19.8

-19.9

-20 -20.1 -20.2

-70.8

-70.6

## **TSUNAMI MODELING WITH UNCERTAIN BATHYMETRY**



#### **SHOULD BE WORRIED?**

## Interpolation of bathymetry from a spectral perspective

We use a conditional random field to model bathymetry uncertainties. This allow to design a random interpolator of bathymetry.



Samples of interpolated bathymetry plus synthetic high-wavenumber content



DEM partially uses satellite bathymetry or sparse ship-board soundings.

-70.2

-70.4

Inami elevation [m]

Maximum

What is the effect of errors?

Sepulveda et al (2020)



## **TSUNAMI MODELING WITH UNCERTAIN BATHYMETRY**

#### **SHOULD BE WORRIED?**

1) Trailing waves (not leading wave) are sensitive to bathymetry errors, even in shallow depths. High sensitivity may be explained by shorter tsunami wavelengths and longer time exposed to large depth relative errors.

2) Leading waves not propagating through shallow depths are not sensitive











## Coastal Engineering Lab



## "... is uncorrupted relationship, taken from the truth, cut to size..."

"La Araucana" by Alonso de Ercilla (1569-89)